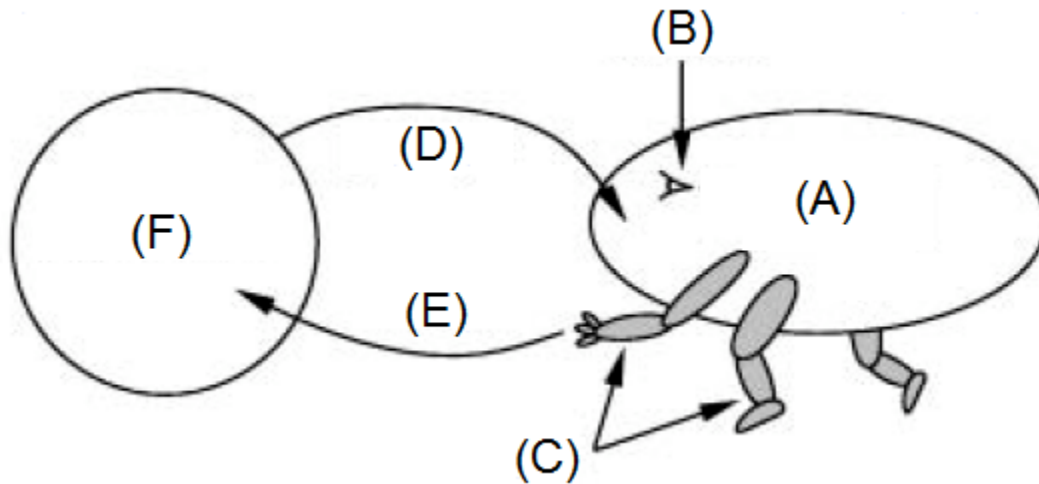
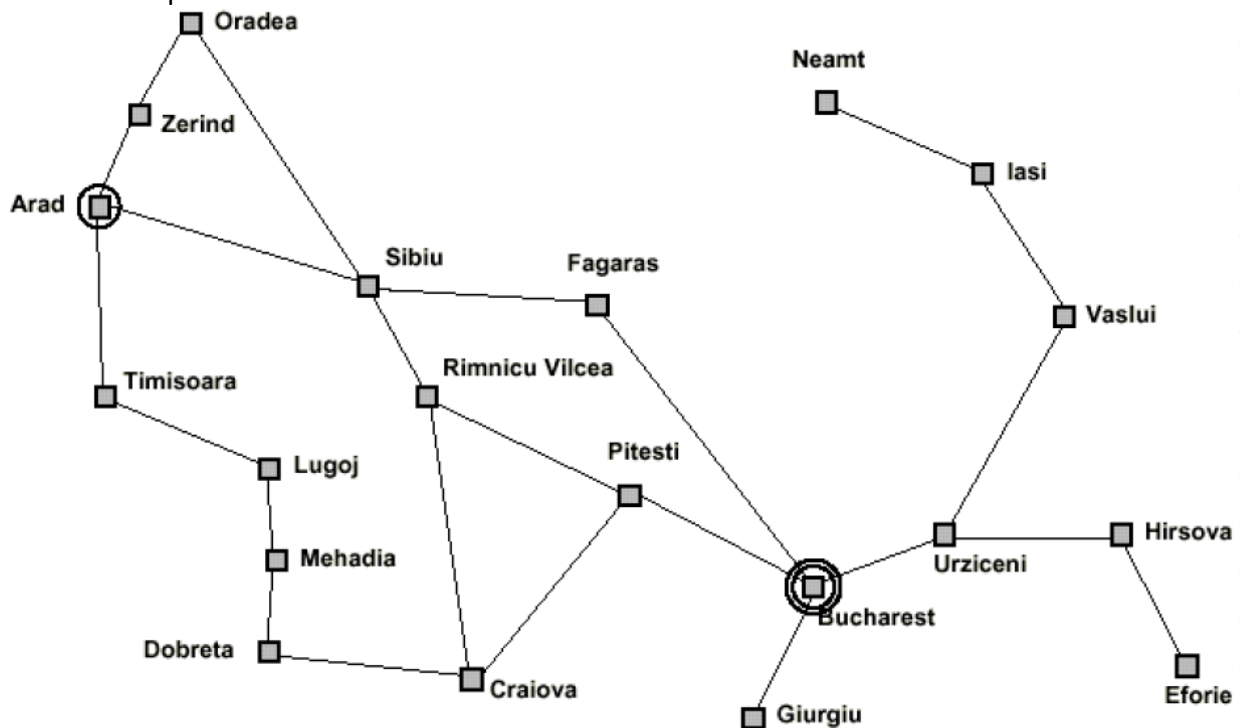


## Potential Midterm Exam Questions

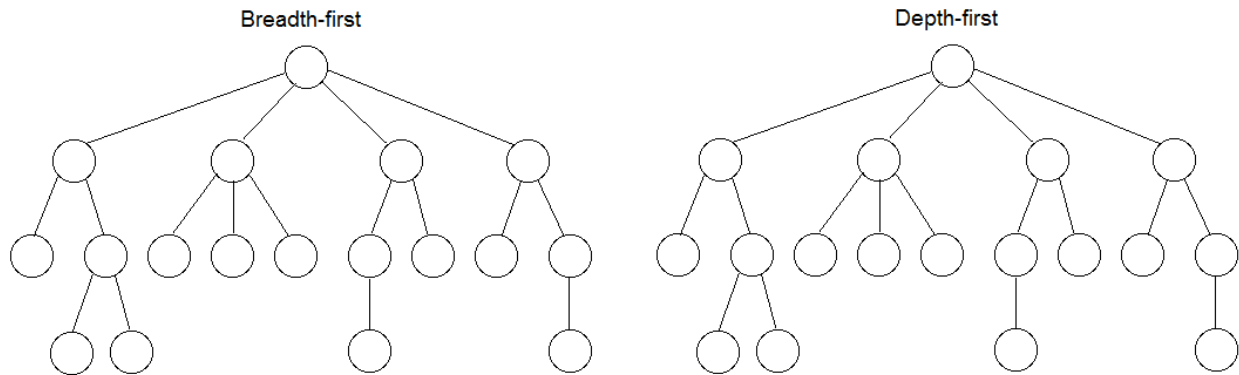
1. What are the four ways in which AI is usually viewed? Which of the four is the preferred view of the authors of our textbook?
2. What does each of the lettered items in the following diagram represent?



3. Rational agents are often specified by a PEAS description. What do each of the letters in the acronym "PEAS" stand for?
4. List, in order of increasing generality, the four basic types of agents we discussed in class.
5. You are in Arad and you want to find a path that will get you to Bucharest. Using the following map, construct the first two levels of a search tree diagram that would be used to solve the problem.



6. For the following trees, number the nodes in the order in which they are explored for breadth-first search and for depth-first search.



7. Fill in the following table:

Environment type \ Game	Solitaire	Chess	Soccer
accessible or hidden			
deterministic or stochastic			
episodic or sequential			
static or dynamic			
discrete or continuous			

8. To evolve from uninformed search to intelligent search, one must add a(n) \_\_\_\_\_ function, which is simply an estimate of \_\_\_\_\_.

9. What must be true about a heuristic in order to call it admissible?

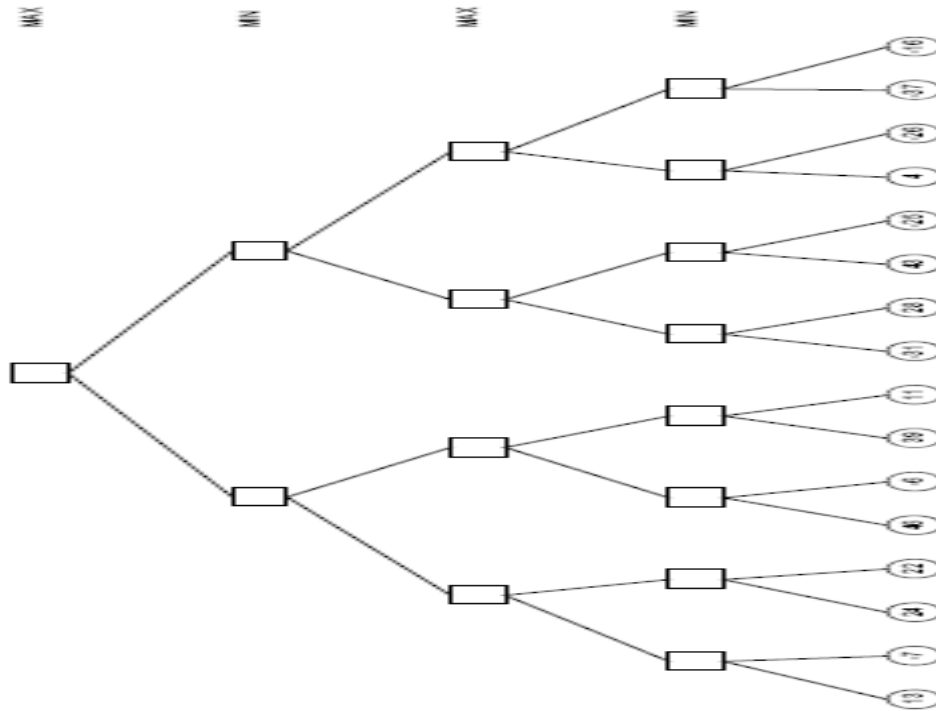
10. Regarding Minimax:

- Is it complete? (Is your answer conditional?)
- Is it optimal?
- What is the time complexity?
- What is the space complexity?

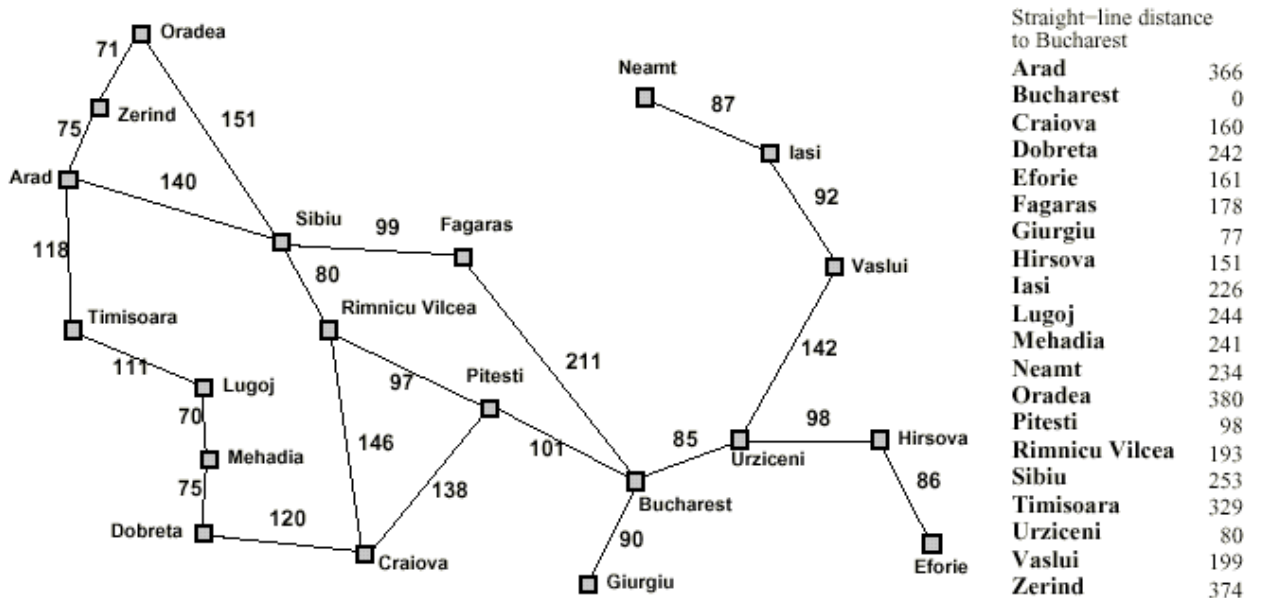
11. Give the following properties for Min-Max algorithm

- Complete?
- Optimal?
- Time complexity?
- Space Complexity?

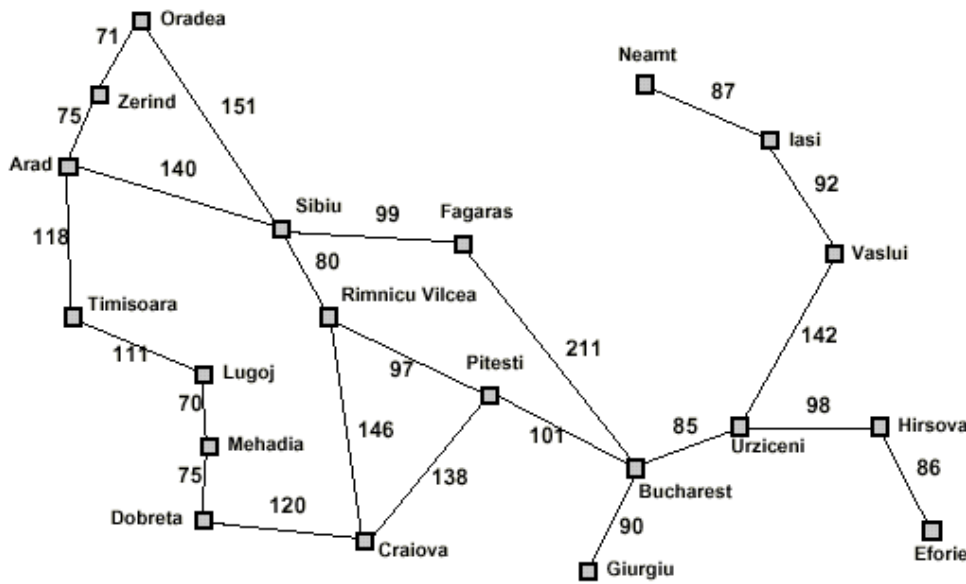
12. Do minmax with alpha beta pruning for the following tree?



13. Find a Path from Arad to Bucharest using Greedy Search technique [ for heuristic apply straight line distance]. Define the four characteristics Optimality, Space and Time Complexity and Completeness for Greedy Search?

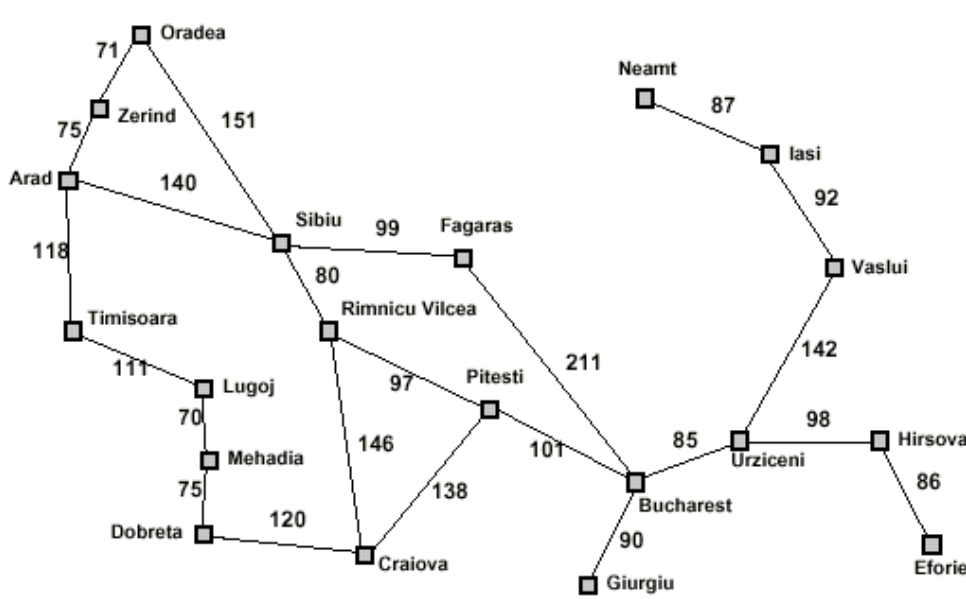


14. Find a Path from Arad to Bucharest using A\* search?

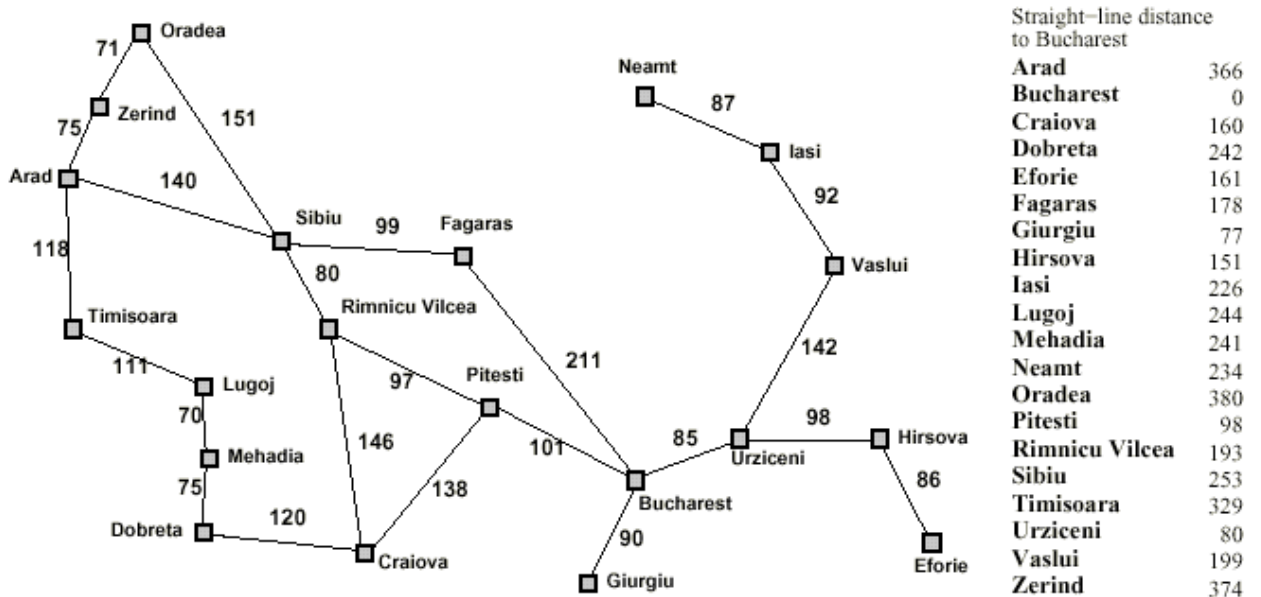


15. Define the four characteristic Optimal, Size Complexity, Time Complexity and Completeness for A\* search? Proof that A\* is optimal? Explain what is admissible Heuristic?

16. How the breadth first searches work? Give example using the following graph? Give characteristic of this search?



17. What is depth first search? Give example with the following graph. Define the characteristic of this search?



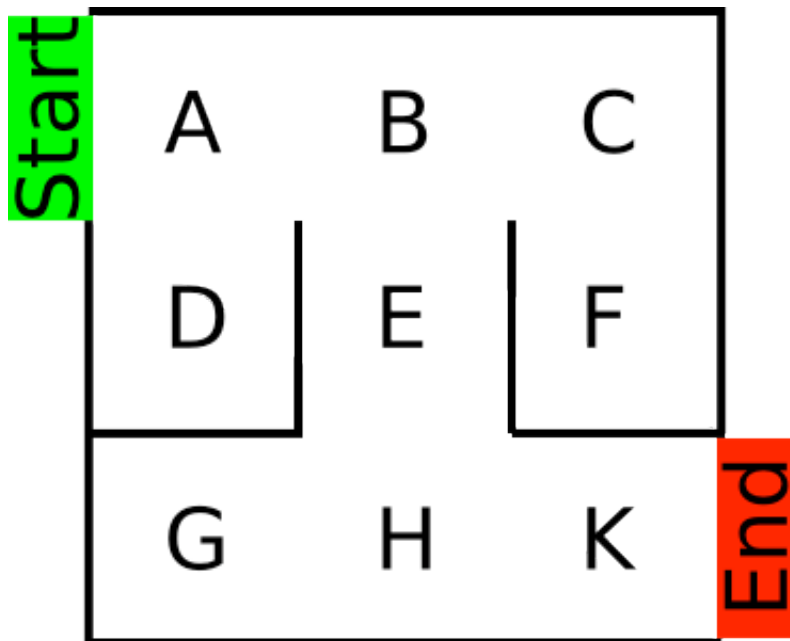
18. Give properties of the depth limited search and iterative deepening search? Give pseudo code for both of the searches.
19. What are the environment types we have seen in our textbook? Give one example of each environment type.
20. Describe the Turing Test. How does it compare with the current direction of artificial intelligence?
21. What four categories do the authors classify the views of artificial intelligence? Which view do the authors follow? Why?
22. What does PEAS stand for? Use it to design an automated vacuum cleaner.
23. Describe and compare the four main types of agents.
24. Compare and contrast breadth-1st search and depth-1st search in terms of completeness and optimality. When might one be used over the other? What are the problems with depth-1st search and how might they be compensated for?
25. Compare and contract greedy search and A\* Search. What heuristics do they use? What advantages does A\* search have over greedy search?
26. What makes an admissible heuristic? Why is this important for search? Explain why using the number of squares in the wrong position for the 8-puzzle is a bad idea even though it is admissible. What is a better heuristic?
27. Games can be classified into four categories using two characteristics. What are the characteristics and some examples of games that fall into the categories?
28. Using minimax, explain why chess is a more "interesting" game than tic-tac-toe. What method can be applied to minimax to improve the results? How does this affect the game of chess?
29. Enumerate the 4 components of the PEAS description of a rational agent and provide 2 examples for each component for the automated vacuum cleaner (i.e. Roomba) example.

30. What assumptions are made about the task environments for which the problem can be solved via search? Name at least two assumptions.
31. Given the following node of a search tree for the 8-puzzle problem, draw the output of the successor function on this node. Assume that repeated states are allowed.

7	2	4
5		6
8	3	1

32. Prove that uniform-cost search is a special case of A\* search.
33. Assume there is an adversarial search problem where at every turn each player is given two choices. Next, consider the evaluation values at  $d=4$  to be 12, 3, 13, 14, 10, 4, 1, 9 (left to right). Assuming that max's turn is next, and that both players are playing optimally, what is max's value?
34. Give two drawbacks to using a depth-first search algorithm.
35. What is the big-O time complexity for the greedy best-first search algorithm?
36. Why is the straight-line distance between two points always an admissible heuristic for the path cost between the two points? Assume that the path cost just takes into account the distance along the path.
37. Consider a tree search algorithm is to be solved via breadth first search. What is the worst-case memory footprint if at every stage of the search there are 3 choices and that the goal state is at a depth of 3? Assume that each node is 1000 bytes.
38. What are the 4 categories of AI?
39. Describe the Turing Test.
40. What is a rational agent?
41. What is the difference between a reflex-based agent and a goal-based agent?
42. Define the following types of environments, and give an example for each:
43. What is the basic difference between uninformed and informed search?
44. Describe A\*. Is it optimal?
45. Describe Minimax. When is it ideal?
46. What is alpha-beta pruning?
47. What change do stochastic games require of the basic minimax? Describe how this change works.
48. Explain why problem formulation must follow goal formulation?
49. Consider a state space where the start state is number 1 and the successor function for state  $n$  returns two states, number  $2n$  and  $2n+1$ .
  - a) Draw the portion of the state space for states 1 to 15.
  - b) Suppose the goal state is 11. List the order in which nodes will be visited for breadth-first search, depth-limited search with limit 3, and iterative deepening search.
  - c) Would bidirectional search be appropriate for this problem? If so describe in details how it works.
50. Describe a state space in which iterative deepening search performs much worse than depth-first search (for example,  $O(n^2)$  vs.  $O(n)$ ?)
51. Trace the operation of A\* search applied to the problem of getting to Bucharest from Lugoj using the straight-line distance heuristic. That is, show the sequence of nodes that the algorithm will consider and the  $f$  and  $h$  score for each node?

52. The heuristic path algorithm is a best-first search in which the objective function is  $f(n) = (2-w)g(n) + wh(n)$ . For what values of  $w$  is this algorithm guaranteed to be optimal? (You can assume that  $h$  is admissible). What kind of search does this perform when  $w=0$ ? When  $w=1$ ? When  $w=2$ ?
53. Prove that Breadth search is a special case of uniform-cost search.
54. Define a game?
55. What is the main difference between minimax and Alpha-Beta algorithm?
56. Both the performance measure and the utility function measure how well an agent is doing. Explain the difference between the two?
57. Can there be more than one agent program that implements a given agent function?
58. Use breadth first search to create a tree from the following maze. Circle objects as they come off of the fringe so that fringe order can be checked.



59. What is the advantage of counting the total cost to the current node when calculating a heuristic?
60. Under what conditions is breadth first search optimal? Why?
61. Is depth first complete? Why?
62. What is greedy search and its major disadvantage?
63. Explain minimax theory for game play.
64. Draw a Simple Reflex Agent.
65. What makes a heuristic admissible?
66. Explain depth limited search.
67. Explain completeness, time complexity, space complexity, and optimality with regard to search.